

# Lagrangian Classical Mechanics: Summer Recap

1. The (classical) simple harmonic oscillator in 1D describes a particle in a potential

$$V(x) = \frac{1}{2}m\omega^2 x^2. \quad (1)$$

Explain why the action for a particle in a simple harmonic oscillator, between times  $t = 0$  and  $t = T$ , is given by

$$S_{\text{SHO}}[x] = \frac{m}{2} \int_0^T dt' (\dot{x}^2 - \omega^2 x^2). \quad (2)$$

**[3 marks]**

$$S = \int dt L$$

**[1 mark]**  
and

$$L = T - V$$

**[1 mark]**  
so

$$\begin{aligned} S &= \int_0^T dt \left( \frac{1}{2}m\dot{x}^2 - \frac{1}{2}m\omega^2 x^2 \right) \\ &= \frac{m}{2} \int_0^T dt (\dot{x}^2 - \omega^2 x^2) \end{aligned}$$

as required.

**[1 mark]**

2. Derive the Euler Lagrange equations for a general action.

**[5 marks]**

We must extremise the action:

$$\left( \frac{\partial S[q_i + \lambda \epsilon_i]}{\partial \lambda} \right)_{q_i, \epsilon_i} \bigg|_{\lambda=0} = 0. \quad (3)$$

The vector function  $\epsilon_i(t)$  parameterises a variation away from the classical path  $q_i(t)$ . We require that the variation is zero at the start and end points of the trajectory:

$$\epsilon_i(t_0) = \epsilon_i(t_f) = 0. \quad (4)$$

Specifically:

$$S[q_i + \lambda \epsilon_i] = \int_{t_0}^{t_f} L(q_i + \lambda \epsilon_i, \dot{q}_i + \lambda \dot{\epsilon}_i, t) dt \quad (5)$$

⇓ chain rule

$$\left( \frac{\partial S[q_i + \lambda \epsilon_i]}{\partial \lambda} \right)_{q_i, \epsilon_i} = \int_{t_0}^{t_f} \left\{ \left( \frac{\partial L}{\partial q_i} \right)_{\dot{q}_i, t} \left( \frac{\partial (q_i + \lambda \epsilon_i)}{\partial \lambda} \right)_{q_i, \epsilon_i} \right. \quad (6)$$

$$\left. + \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} \left( \frac{\partial (\dot{q}_i + \lambda \dot{\epsilon}_i)}{\partial \lambda} \right)_{q_i, \epsilon_i} + \left( \frac{\partial L}{\partial t} \right)_{q_i, \dot{q}_i} \left( \frac{\partial t}{\partial \lambda} \right)_{q_i, \epsilon_i} \right\} dt \quad (7)$$

$$= \int_{t_0}^{t_f} \left\{ \left( \frac{\partial L}{\partial q_i} \right)_{\dot{q}_i, t} \epsilon_i + \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} \dot{\epsilon}_i \right\} dt \quad (8)$$

Now integrate the  $\dot{\epsilon}$  term by parts in Eq 8:

$$\left( \frac{\partial S[q_i + \lambda \epsilon_i]}{\partial \lambda} \right)_{q_i, \epsilon_i} = \int_{t_0}^{t_f} \left\{ \left( \frac{\partial L}{\partial q_i} \right)_{\dot{q}_i, t} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} \right\} \epsilon_i dt + \left[ \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} \epsilon_i \right]_{t_0}^{t_f} \quad (9)$$

but the boundary term vanishes by assumption. Applying the principle of least action, Eq 3, we require

$$\left( \frac{\partial S[q_i + \lambda \epsilon_i]}{\partial \lambda} \right)_{q_i, \epsilon_i} \Big|_{\lambda=0} = 0 = \int_{t_0}^{t_f} \left\{ \left( \frac{\partial L}{\partial q_i} \right)_{\dot{q}_i, t} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} \right\} \epsilon_i dt. \quad (10)$$

This is true for all  $\epsilon_i(t)$  (since this arbitrary function has not been specified). This gives

$$\left( \frac{\partial L}{\partial q_i} \right)_{\dot{q}_i, t} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}_i} \right)_{q_i, t} = 0. \quad (11)$$

**3.** Show that classical trajectories of the Harmonic oscillator  $x_c(t)$  obey

$$\ddot{x}_c = -\omega^2 x_c. \quad (12)$$

**[3 marks]**

Classical trajectories obey the Euler Lagrange equations:

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) - \frac{\partial L}{\partial x} = 0$$

**[1 mark]**

giving

$$\frac{d}{dt} (m\dot{x}) - (-m\omega^2 x) = 0$$

**[2 marks]**, one for each part, or

$$m\ddot{x} + m\omega^2 x = 0$$

which simplifies to the stated expression.

**4.** Solve for the classical trajectory  $x(t)$  assuming  $x(t=0) = 0$  and  $x(t=T) = X$ .

[3 marks]

The general solution is

$$x_c = A \sin(\omega t) + B \cos(\omega t)$$

[1 mark]

and substituting the boundary conditions gives

$$x = X \frac{\sin(\omega t)}{\sin(\omega T)}$$

[2 marks].

5. Hence evaluate the action between times 0 and  $T$ , subject to these same boundary conditions. Check that your answer has the correct dimensions.

[3 marks]

Insert the expression into the action:

$$\begin{aligned} S_{\text{SHO}}[x] &= \frac{m}{2} \int_0^T dt' (\dot{x}^2 - \omega^2 x^2) \\ &= \frac{mX^2\omega^2}{2\sin^2(\omega T)} \int_0^T dt' (\cos^2(\omega t) - \sin^2(\omega t)) \\ &= \frac{mX^2\omega^2}{2\sin^2(\omega T)} \int_0^T dt' (\cos(2\omega t)) \\ &= \frac{mX^2\omega}{4\sin^2(\omega T)} [\sin(2\omega t)]_0^T \\ &= \frac{mX^2\omega \sin(2\omega T)}{4\sin^2(\omega T)} \\ &= \frac{1}{2} m\omega X^2 \cot(\omega T). \end{aligned}$$

[2 marks]

To check the dimensions, note that

$$[S] = \mathbb{E}\mathbb{T}$$

and since

$$\left[ \frac{1}{2} m\omega X^2 \right] = \left[ \frac{1}{2} m\omega^2 X^2 \right] [\omega^{-1}] = \mathbb{E}\mathbb{T}$$

this works out. Strictly there are some dimensionless radians in there, but they actually make sense if thought about systematically (e.g.  $E = hf = \hbar\omega$ , and  $h$  and  $\hbar$  have the same units).

[1 mark]

6. Find the momentum  $p$  conjugate to the position  $x$  for the classical harmonic oscillator.

[2 marks]

$$p \triangleq \frac{\partial L}{\partial \dot{x}}$$

**[1 mark]**  
giving

$$p = m\dot{x}$$

**[1 mark]**

7. By performing a Legendre transform on the Lagrangian  $L(\dot{x}, x)$ , derive the Hamiltonian of the simple harmonic oscillator  $H(p, x)$ .

**[3 marks]**

To calculate the Hamiltonian from the Lagrangian:

$$H(x, p) = p\dot{x} - L(x, \dot{x})$$

**[1 mark]**  
giving

$$H(x, p) = p\dot{x} - \left( \frac{1}{2}m\dot{x}^2 - \frac{1}{2}m\omega^2 x^2 \right)$$

**[1 mark]**

and we now need to eliminate  $\dot{x}$  in favour of  $p$ :

$$\begin{aligned} H(x, p) &= p^2/m - \left( \frac{1}{2}p^2/m - \frac{1}{2}m\omega^2 x^2 \right) \\ &= \frac{p^2}{2m} + \frac{1}{2}m\omega^2 x^2. \end{aligned}$$

**[1 mark]**

8. Sketch the phase space trajectories for the classical harmonic oscillator.

**[3 marks]**

The trajectories are clockwise **[1 mark]** circles **[1 mark]** centred on the origin **[1 mark]**.